

CONTROL OF SMART STRUCTURES USING OUTPUT FEEDBACK CONCEPTS**S.M. Kusagur¹, G. Arunkumar² and T.C.Manjunath³**¹VTU RRC, Belagavi, Karnataka, India²Department of Electronics & Communication Engg., JSS Academy of Technical Education (JSSATE), Noida, UP, India³Department of Electronics & Communication Engg., Dayananda Sagar College of Engineering, Shavigemalleshwara Hills, Kumaraswamy Layout, Bangalore, Karnataka, India

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ABSTRACT

In this research paper, an exhaustive review of controlling of the smart intelligent structures is presented. This paper gives a summary of the various types of controlling techniques that are being used by various authors across the world in the field of controller design, the paper also serves as a ready reckoner for all the researchers who want to pursue a career in this exciting field of smart intelligent structures.

Keywords: Smart structure, Intelligence, Smart materials, Controller.

1. Introduction

In this part, a comprehensive audit of the ideas that are identifying with the dynamic vibration concealment or control in brilliant canny structures utilizing assortments of clever materials as sensors and actuators for a normal adaptable aluminum cantilever shaft is introduced. The primary worry of the exploration work is the pillar is like the rectangular wing of a lightweight flyer airplane which is pivoted toward one side and the opposite end being free. We as a whole understand what when the wing is noticeable all around and is in dynamical movement, it is followed up on by an outer power f_{ext} .

The adaptable pillar will be then exposed to the vibrations, might be in the cross over more or in the rotational mode. These cross over or longitudinal or rotational vibrations ought not continue in the dynamical framework for a long measure of time and whenever allowed to do as such, the life expectancy and dependability of the framework will be decreased, exposed to mileage, framework execution breakdowns. These cross over vibrations ought to be smothered or made to rot

as ahead of schedule as conceivable when the framework is in activity itself. This should be possible by the improvement of complex regulators utilizing the idea of input hypothesis.

In the ongoing 21st century, the vibration control of the dynamical framework utilizing brilliant smart materials, for example, Piezoelectric, Shape Memory Alloys (SMA), Electro Rheological Fluids (ERF), Magneto Rheological Fluids (MRF), Poly Vinyl Derelyne Fluoride (PVDF), Accelerometers, Optic filaments, Carbon Nano-Tubes (CNT), Thermistors, LVDT, Pyro-Electrics (PE), Piezo-Ceramics (PC), and so forth... has gotten exceptionally extraordinary consideration and has become a significant issue in an adaptable or inflexible structures, for example, the pillars, plates, shells, segments, swaggers, docks, wings, structures, airplanes, and so on... , that too after the event of quakes, torrents, twin pinnacle debacles, and so on. The Fig. No. 1 gives the block diagram of the active vibration suppression in smart intelligent structures.

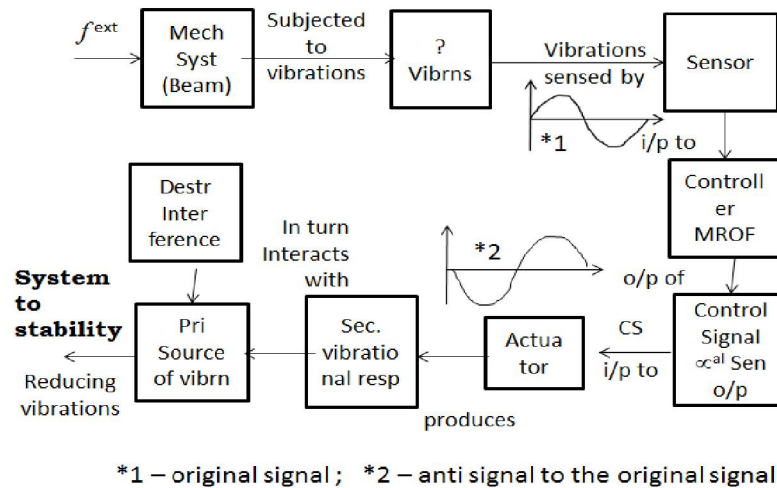


Fig. 1 : Block diagram of the active vibration suppression in smart intelligent structures

2. Literature Survey

An enormous number of analysts have taken a shot at the theme, “Multivariable Modeling of Intelligent Flexible Mechanical Structures utilizing Smart Materials with FEM, Euler-Bernoulli bar hypothesis, State Space and Multi-Sensor Data Fusion Techniques”. In this part, a short survey of the work done by different creators is being given their points of interest and downsides. First and foremost, 100's of examination papers were gathered from different sources, considered @ length and expansiveness. Here, just a thorough writing study [1] – [20] of the exploration works done by different writers over the globe till date is being introduced w.r.t. the work taken up in this energizing and application-situated field of savvy material science. A typical smart intelligent structure consists of a sensor, actuator, active & sensitive structures all embedded into the structure, the overall configuration is shown in the Fig. 2.

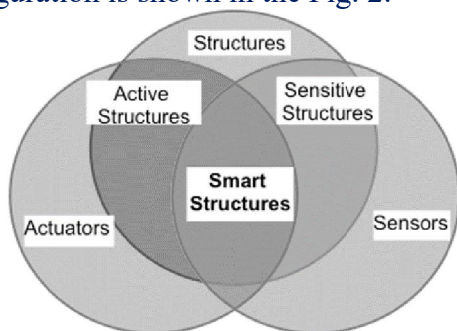


Fig. 2 : Overall component layout of a smart intelligent structure

Poly Vinylidene Fluoride (PVDF) subordinate sensors and actuators has numerous

applications, to give some examples of them, in structure wellbeing checking SHM [1], vibration detecting VS [2] and car applications [3] and in [4]. In the paper in the reference [20], the creators introduced the new information and techniques for PVDF-based sensor and actuator models for estimating the misshapening and movement in the mechanical frameworks. 2 kinds of uses was created in [15] which inspired the creators to consider the PVDF-based twisting and movement detecting components, which were for the RT car tire disfigurement estimation and the subsequent one being for diversion of the creepy crawly locomotion's. Tire/street collaboration assumes a significant part for safe tasks of the vehicles [5]. Track disfigurement is the basic data for getting tire/street collaborations [6], [7]. In the paper in [8], the writers introduced a measure to the twisting of the tire strings. Surface acoustic wave (SAW) sensors had been proposed for an awesome tire application in the paper distributed in the reference [9]. Capacitance based PVDF sensors have been produced for checking the twisting of the tires [10]. In the papers in [11] and [12], the utilization of PVDF-depended miniature sensors were utilized to gauge the disfigurement of the strings. It very well may be obviously observed that the estimations of the sensor will relate to the outspread misshapening of the tires. A nitty gritty report for the improvement of the detecting of the tires framework utilizing PVDF, including the remote information transmission module was

distributed in [6], [11], and [12]. In the paper in [13], a PVDF subordinate dainty film sensor was accounted for to quantify the velocity of the leg of a cockroach.

As for the overall movement of the 2 closures of the sensor, the PVDF based slender film was clasped and sensors were made to produce electric charges because of bowing movement on account of the pressure/strain energy connection. Such another detecting configuration was diverse with the greater part of the PVDF based detecting applications. A lion's share of the PVDF based applications require exceptionally high piezo-power and the dependability of the PVDF material for the plan of the sensor as introduced in [14]. In this paper, the PVDF numerical model introduced in [15] is being utilized to display the sensor actuator pair of the PVDF pillar component and is utilized for the dynamic vibration control.

A concise audit of the numerical demonstrating of effectively controlled piezo-brilliant structures was advanced in a review paper by Vivek Gupta et.al. in [16], where they displayed the piezo electric sensors, piezo electric actuators and delivered some novel outcomes in comparison with the work done by others. The writers examined 4 significant focuses, viz., composing the conditions of movement, actualizing a sensor-actuator configuration, building up the model, all things considered, ecological impacts and obviously thinking about the controlled auxiliary vibrations. Redirection of a coupled flexibility electrostatic bimorph with PVDF material which prompted the hypothetical, FEM and trial confirmations was done by Muhammad Usman Khan in his exploration paper in [17]. In this paper, a 2D bimorph piezoelectric actuator model which was comprised of 2 layers of poly vinylidene fluoride (PVDF) material was created to analyze the opposite piezoelectric impacts.

Charm Seok Hwang and Hyun Chul Park created limited component models of piezo sensors and actuators in their contributed paper in [18], where they utilized the hamilton's standard to figure the condition of movement. Mathematical reenactment of the o/p reaction of a PVDF sensor which was joined to an adaptable cantilever shaft and which was exposed to unexpected effect stacking was explored upon by Cao Vu Dung et.al. in [19] and indicated that the PVDF sensors displayed superb detecting abilities for the in-plane powerful strains actuated because of the effect loadings at the impasse of the adaptable cantilever pillar. A Finite Element Method based-State Space Approach was utilized in the demonstrating, control and execution of brilliant structures in the monograph distributed by Bijnan Bandyopadhyay et.al. in [20] which was utilized in the ebb and flow research paper for the numerical demonstrating cycle to show up at the multivariable based multi-sensor model.

Conclusions

This review paper gave a brief idea about the type of research that is going on in the field of smart intelligent structures. The paper can be used by any research scholar for their proposed research works. This paper gave a brief summary of the various types of controlling techniques that are being used by various authors across the world in the field of controller design, the paper also serves as a ready reckoner for all the researchers who want to pursue a career in this exciting field of smart intelligent structures.

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